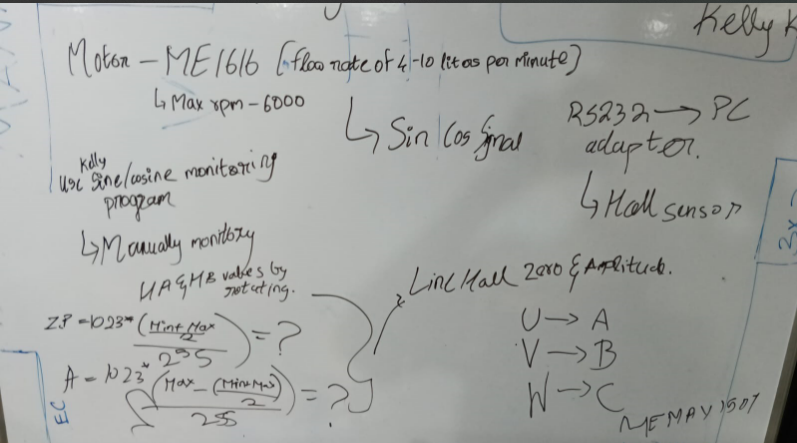
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Started with LVS(Low Voltage System) .. Figured out the speedometer working and GPS configuration with ESP32 and Raspberry PI (Unfortunately ESP32 is not working and we need a memory card for the raspberry pi)

Then moved to HVS(High Voltage System) :

Took out the description of the Motor ME1616, Kelly Controller (KLC 96601) and understanding the wirings from the motor and KLC ..

Understanding the conversion of hall sensor to sine cosine



Text

Description automatically generated